Trello Board

<https://trello.com/b/wRyoYxwN/final-project-sprint-board>

Gazebo Sim Repo

[https://github.com/nubot-nudt/gazebo\_visual](https://github.com/nubot-nudt/gazebo_visual?fbclid=IwAR0Ta9owz-yIfrm6-dBtlzjrmjlRt2Gstc32hs8d0EugiwdYyAcqv_4sCQk)

Sim papers

[2017\_Book\_RobotOperatingSystemROS.pdf](https://drive.google.com/file/d/1vJV61tJQV1jp8DS7wcSJQVOZmitz1zKj/view?usp=sharing)

Planning

[A\*](http://home.iitk.ac.in/~anuj/docs/soccer.pdf)

[Survey of Robot 3D Path Planning Algorithms](https://www.hindawi.com/journals/jcse/2016/7426913/)

[subtargets\_and\_bspline.pdf](https://drive.google.com/file/d/1ldaQcc2WGM7Qg3iLmCwSUskfyxmMHB2Q/view?usp=sharing)